

VIII El grupo de Renormalización

R.G.

1) Invariancia de escala para los puntos críticos

{ $\rightarrow \infty \rightarrow$ inv. de escala
 \rightarrow estado fractal.

\rightarrow "Alejarse" del sistema para borrar los detalles microscópicos
 \rightarrow comportamiento universal del fractal.

\rightarrow Concepto de clase de Universalidad (K. Wilson)

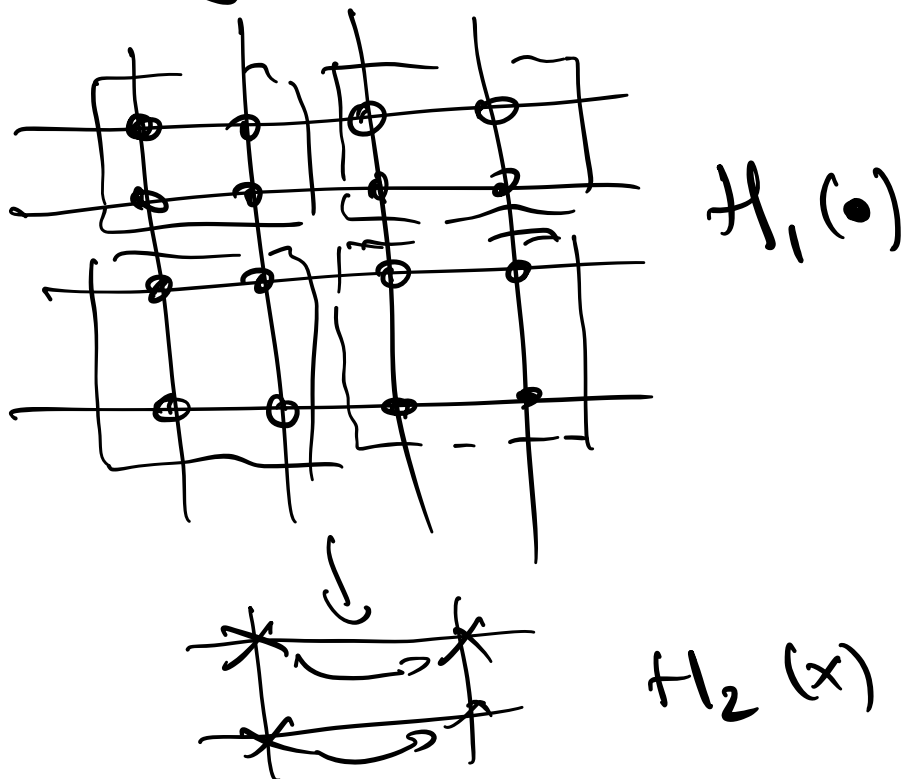
la clase de unicoidalidad de
 en punto crítico depende de

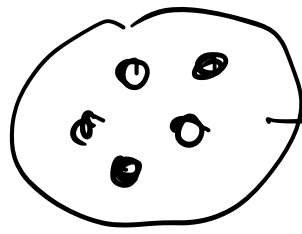
- la dim. del espacio
- el grupo de la simetría

que siempre

2) R.G. en el espacio real

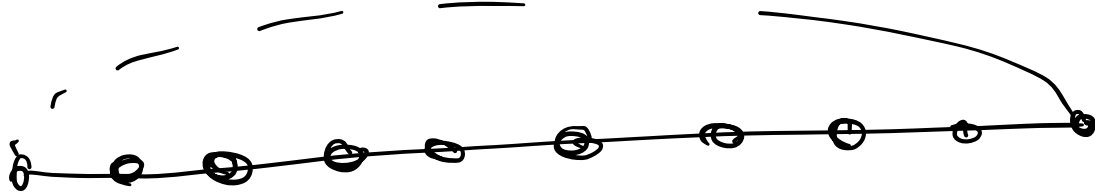
(L. Kadanoff)





$$\sigma_{\text{eff}} = \begin{cases} +1 & \text{si } \sigma_i \sigma_{i+1} > 0 \\ -1 & \text{si } \sigma_i \sigma_{i+1} < 0 \end{cases}$$

⇒ el caso en 1-D

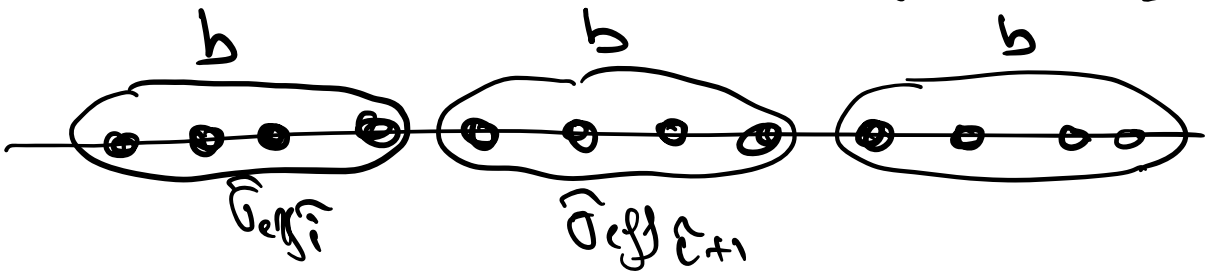


$$H = -J \sum_i \sigma_i \sigma_{i+1}, \quad K = \frac{J}{k_B T}$$

$$Z = \text{Tr} \left(T^N \right); \quad T = \begin{pmatrix} e^K & e^{-K} \\ e^{-K} & e^K \end{pmatrix}$$

$$Q = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{pmatrix}$$

$$Q T Q = \begin{pmatrix} 2 \cosh K & 0 \\ 0 & 2 \sinh K \end{pmatrix}$$



→ una cadena de $\tilde{N} = \frac{N}{b}$ espinas

→ un nuevo Hamiltoniano de Ising

$$\tilde{T} \quad \text{tg} \quad z = \det z \left(\tilde{T} \right)$$

$$\Rightarrow \tilde{T} \neq T^b \quad \text{sin} \quad \tilde{T} = \det T^b$$

$$\Theta \tilde{T} \Theta = \begin{pmatrix} 2 \cosh \tilde{k} & 0 \\ 0 & 2 \sinh \tilde{k} \end{pmatrix}$$

$$\begin{pmatrix} (2 \cosh \tilde{k})^b & 0 \\ 0 & (2 \sinh \tilde{k})^b \end{pmatrix} = \det \begin{pmatrix} 2 \cosh \tilde{k} & 0 \\ 0 & 2 \sinh \tilde{k} \end{pmatrix}$$

$$\Theta T^b \Theta$$

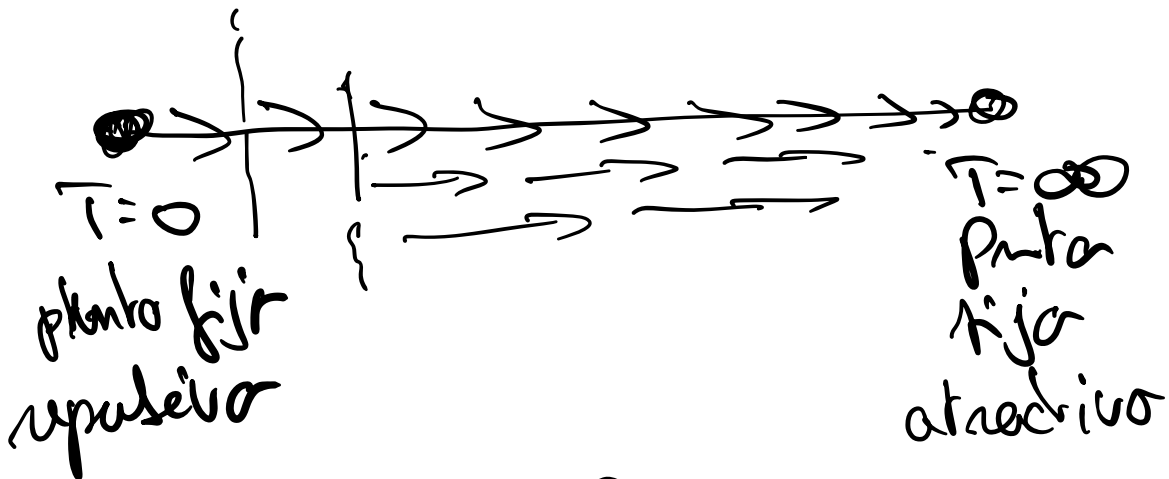
$$t_h(k) = (T_h(k))^b$$

$$\Rightarrow \boxed{\hat{k} = th^{-1} [th(k)^b]}$$

esta recursión tiene 2 puntos fijos

$$th k = 0 \quad (T = \infty)$$

$$th k = 1 \quad (T = 0)$$

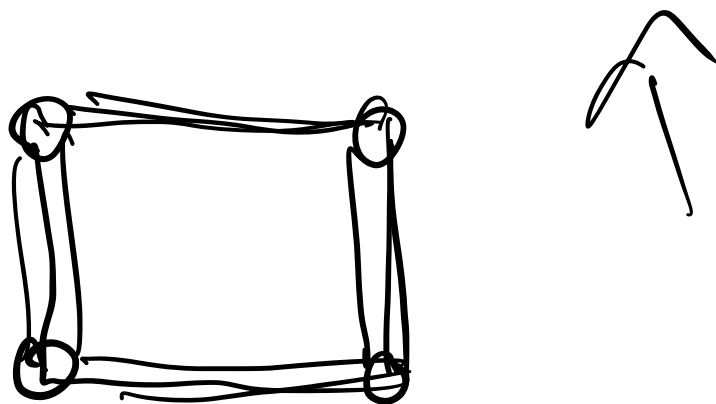
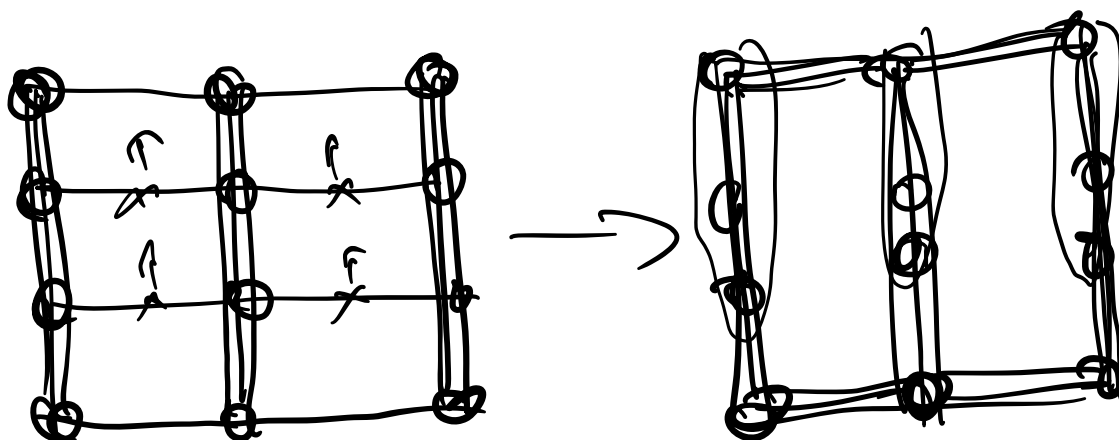
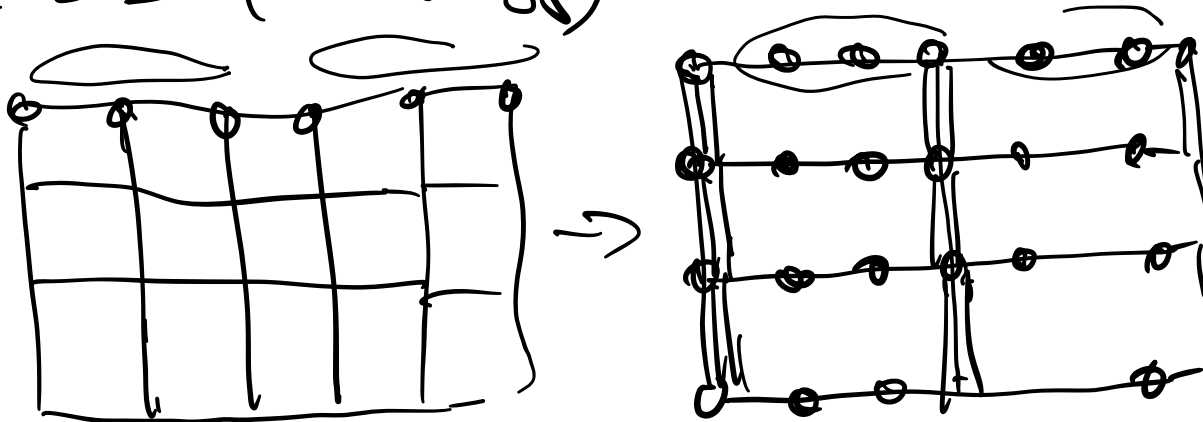


ej: mostrar que $\hat{\gamma} \leftrightarrow \hat{k}$

$$\hat{\gamma} \leftrightarrow \hat{k}$$

$$\Rightarrow \boxed{\hat{\gamma} = \frac{\hat{\rho}}{b}}$$

en 2-D (Kadomoff)



$k \rightarrow bk$ 1^{er} étape

$K \rightarrow th^{-1} [th(k)^b]$ 2^e étape

$$k \rightarrow bk$$

$$\hat{k} = b \operatorname{th}^{-1} \left[\operatorname{th}(bk) \right]$$

b entero, \rightarrow prolongación
 $a, b \in \mathbb{R}$

$$b \approx e^{\delta l} \approx (1 + \delta l) \quad \delta l \ll 1$$

$$\operatorname{th}^{-1} \left[\operatorname{th} \left[(1 + \delta l) k \right] \right]$$

$$\approx (1 + \delta l) k + \delta l \left[\frac{1}{2} \operatorname{sh} \epsilon k \operatorname{th}^{-1} \left[\operatorname{th}(k) \right] \right] + \mathcal{O}(\delta l^2)$$

$$\hat{k} = k + \delta k$$

$$\frac{\delta k}{\delta l} \rightarrow \frac{dk}{dl}$$

$$\Rightarrow \frac{dK}{d\ell} = K + \frac{1}{2} [\text{sh}(2K) \ln(\text{th}(K))]$$

para $D \geq 2$

$$\frac{dK}{d\ell} = (D-1)K + \frac{1}{2} [\text{sh}(2K) \ln(\text{th}(K))]$$

$$\epsilon = \frac{D-1}{2}$$

$$T = \frac{J}{k_B T} \quad \text{a} \quad K = \frac{J}{k_B T}$$

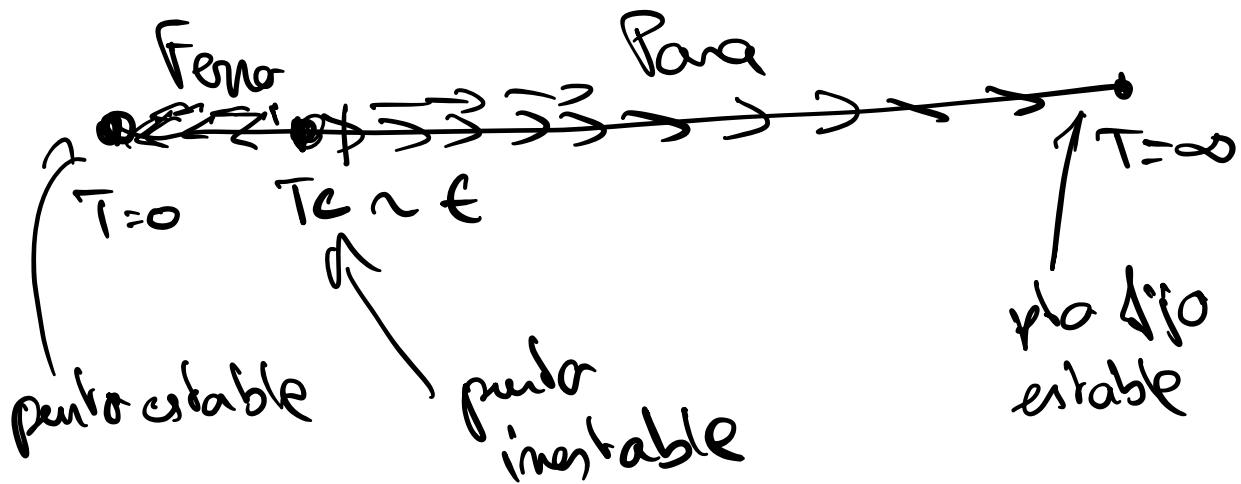
T pequeña

$$\frac{dT}{d\ell} = -\epsilon T + \frac{k_B}{2J} T^2 + \mathcal{O}(T^3)$$

\rightarrow 2 puntos críticos por T pequeña

$$* T = 0$$

$$* T_c = \frac{2J\epsilon}{k_B}$$



$$T = T_c + \delta T$$

$$\frac{d\delta T}{d\ell} = \epsilon \delta T$$

$$T = 0 + \delta T$$

$$\frac{d\delta T}{d\ell} = -\epsilon \delta T$$

$$\delta T(\ell) = e^{\epsilon \ell} \delta T(0)$$

$$f(\ell) = e^{-\ell} f(0) \leftarrow$$

$$\psi(\rho) \sim e^{-\rho}$$

$$\psi(\rho) \sim (\delta T)^{-\nu} \sim e^{-\rho}$$

$$\Rightarrow \boxed{\nu = \frac{1}{e}}$$

3) R.G. para la teoría de Campos.

$$S_{GL} = \int d^d \vec{h} \left[\frac{\kappa}{2} (\nabla \phi)^2 + \frac{t}{2} \phi^2 + \mu \phi^4 + \mu_6 \phi^6 + \mu_8 \phi^8 \right]$$

$$t = \frac{T - T_c}{T_c}$$

$$\text{si } t = \mu = \mu_6 = \mu_8 = \dots = 0$$

→ invariante de escala

$$\left\{ \begin{array}{l} \kappa \rightarrow b^{\frac{1}{2}} \kappa' \\ \phi \rightarrow b^{-\frac{1-D}{2}} \phi' \end{array} \right. \quad \underline{\kappa \rightarrow \kappa} \quad b > 1$$

ahora si $t \neq 0$, $\mu \neq 0$ etc...

$$\begin{aligned} \vec{h} &\rightarrow b \vec{h}' & \sigma & \vec{h}' = \frac{1}{b} \vec{h} \\ \vec{g} &\rightarrow b \vec{g}' & \rho & \vec{g}' = \frac{1}{b} \vec{g} \\ \phi &\rightarrow b^{-1/2} \phi' \end{aligned}$$

$$\left. \begin{aligned} t &\rightarrow b t = t' \\ \mu &\rightarrow b^{4-D} \mu = \mu' \end{aligned} \right\}$$

$$\begin{aligned} \underline{\mu_6} &\rightarrow b^{6-2D} \mu_6 = \mu'_6 \\ \underline{\mu'_8} &= b^{8-3D} \mu_8 \end{aligned}$$

abs si $t \neq 0$, $t' > t \rightarrow t'' > t' > t$
etc.

abs. $t \sim \frac{1}{f^2}$

si $t \neq 0 \rightarrow$ no hay intr. de escala

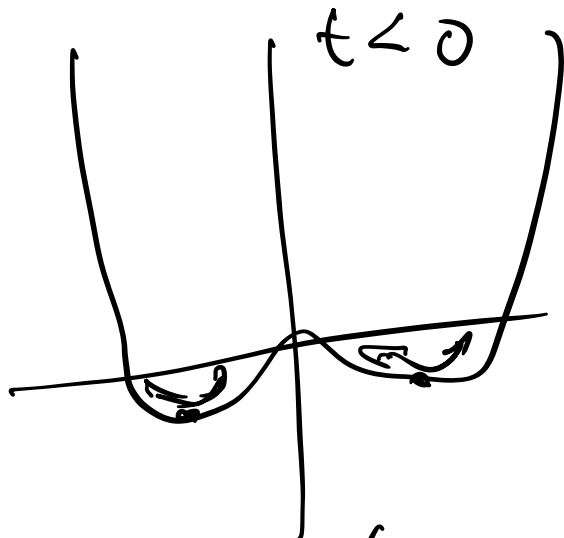
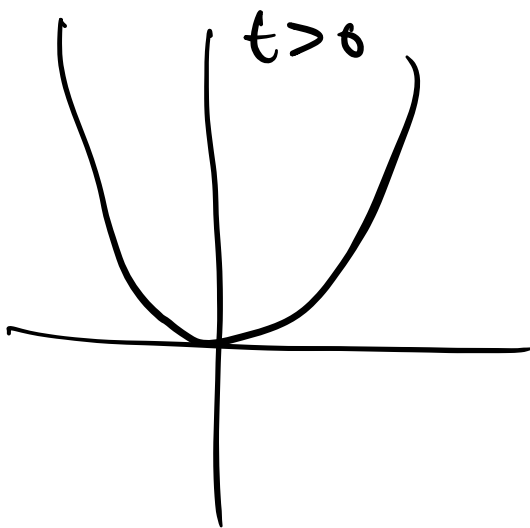
obs 2 $\mu' = b^{\frac{h-D}{2}} \mu$ $b > 1$

si $D > 4$ $\mu' < \mu$

$\rightarrow \mu'' < \mu' < \mu$

con el R.G. $\mu \rightarrow 0$ si $D > 4$

idem μ_0, μ_8 etc. -



para $D \geq 4 \rightarrow$ la aproximación
gausiana se justifica.

\rightarrow los resultados de campo medio
son válidos!

4) R.G. perturbativo para la
teoría de campos

$$Z = \int \mathcal{D}\phi e^{-S_{G.L.}}$$

$$= \int \mathcal{D}\phi e^{-\int d^4x \left[\frac{1}{2} \dot{\phi}^2 + \frac{\kappa}{2} (\nabla\phi)^2 \right] - U}$$

donde $U = \mu \int d^4x \phi^4 + \dots$

$$n(\vec{q}) = \int d^4x e^{i\vec{q}\cdot\vec{x}} \phi(\vec{x})$$

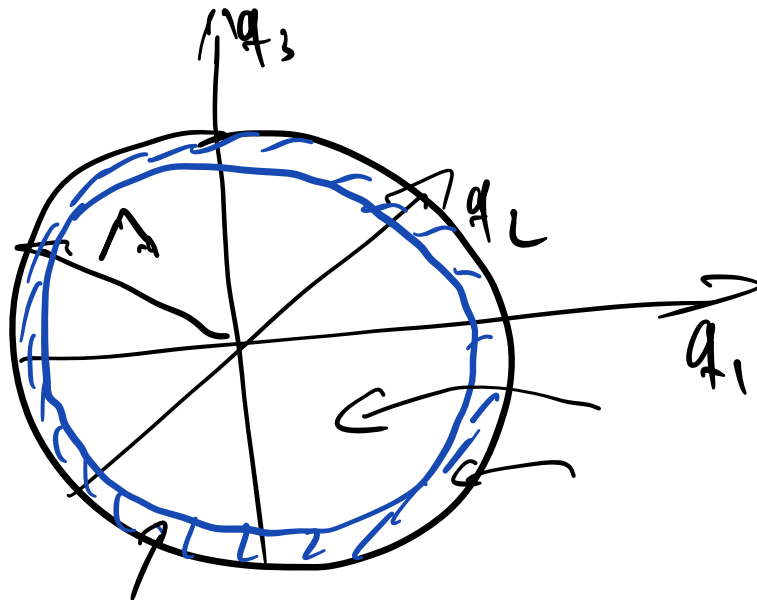
$$\phi(\vec{x}) = \int \frac{d^4q}{(2\pi)^4} e^{-i\vec{q}\cdot\vec{x}} n(\vec{q})$$

$$S_0 = \int \frac{d\vec{q}}{(2\pi)^D} \left(\frac{t + \kappa \vec{q}^2}{2} \right) \underline{\underline{|m(\vec{q})|^2}}$$

$$U = \mu \int \frac{d\vec{q}_1 d\vec{q}_2 d\vec{q}_3}{(2\pi)^{3D}} \frac{m(\vec{q}_1) m(\vec{q}_2) m(\vec{q}_3)}{m(\vec{q}_1 + \vec{q}_2 + \vec{q}_3)}$$

→ out-off O.V.

$$|\vec{q}| \leq \Lambda \sim \frac{1}{a_0}$$



$$\frac{\Lambda}{b} < |\vec{q}| \leq \Lambda \quad b > 1$$

la idea es integrar los $m(\vec{q})$
que están en la cáscara.

$$m(\vec{q}) \begin{cases} \hat{m}(\vec{q}) & \text{si } 0 < q \leq \frac{\Lambda}{b} \\ \sigma(\vec{q}) & \text{si } \frac{\Lambda}{b} < q \leq \Lambda \end{cases}$$

para S_0 hay desacople

$$S_0 = \int_{\frac{\Lambda}{b}}^{\Lambda} \frac{d^d q}{(2\pi)^D} \left(\frac{t + kq^2}{2} \right) |\hat{m}(\vec{q})|^2 = S_0(\hat{m})$$

$$+ \int_{\frac{\Lambda}{b} < q < \Lambda} \frac{d^d q}{(2\pi)^D} \left(\frac{t + kq^2}{2} \right) |\sigma(\vec{q})|^2 = S_0(\sigma)$$

$$Z = \int \mathcal{D}\bar{\psi}(\bar{q}) \mathcal{D}\psi(q) \underbrace{e^{-S_0(\bar{\psi}) - S_0(\psi)} e^{-\mathcal{U}[\bar{\psi}, \psi]}}_{-S_0(\psi)}$$

$$\underline{Z_0 = \int \mathcal{D}\sigma(\bar{q}) e^{-S_0(\sigma)}}$$

$$\underline{\delta F_0 = \ln Z_0}$$

$$\underline{\langle \sigma \rangle_\sigma = \frac{1}{Z_0} \int \mathcal{D}\sigma(\bar{q}) \sigma e^{-S_0(\sigma)}}$$

$$Z_{\text{eff}} = \int \mathcal{D}\bar{\psi}(\bar{q}) e^{-S_0(\bar{\psi})} \underbrace{\int \mathcal{D}\sigma(\bar{q}) e^{-S_0(\sigma) - \mathcal{U}[\bar{\psi}, \sigma]}}_{Z_0 \langle e^{-\mathcal{U}[\bar{\psi}, \sigma]} \rangle_\sigma}$$

$$= \int \mathcal{D}\bar{\psi}(\bar{q}) e^{-S_0(\bar{\psi})} \underbrace{Z_0 \langle e^{-\mathcal{U}[\bar{\psi}, \sigma]} \rangle_\sigma}_{Z_0 \langle e^{-\mathcal{U}[\bar{\psi}, \sigma]} \rangle_\sigma}$$

$$Z_{\text{eff}} = \int \mathcal{D}\vec{m}(\vec{r}) e^{-S_{\text{eff}}(\vec{m})}$$

$$S_{\text{eff}}(\vec{m}) = S_0(\vec{m}) + \cancel{\delta S} - \ln \langle e^{\vec{u}} \rangle_0$$

\uparrow \uparrow \uparrow
 reconnection \vec{m} situation
 \vec{m}

$$\ln \langle e^{-u} \rangle_0 = -\langle u \rangle_0 + \frac{1}{2} (\langle u^2 \rangle_0 - \langle u \rangle_0^2)$$

\downarrow \uparrow $+$ $-$ \uparrow

$$\langle 1 - u + \frac{1}{2} u^2 + \dots \rangle$$