

$$S_{G.L}(\phi) = \int d\vec{r} \left[\frac{c}{2} (\nabla \phi)^2 + \frac{a_2}{2} \phi^2 + \frac{a_4}{4} \phi^4 + \frac{a_6}{6} \phi^6 + \dots \right]$$

→ simetría \mathbb{Z}_2 $\phi(\vec{r}) \rightarrow \begin{cases} \phi(\vec{r}) \\ -\phi(\vec{r}) \end{cases}$

$$a_2 = a t \quad ; \quad t = \frac{T - \tilde{T}_c}{T_c} \quad \begin{cases} t > 0 \quad \tilde{T} > \tilde{T}_c \\ t < 0 \quad \tilde{T} < \tilde{T}_c \end{cases}$$

el caso
 $a_4 > 0$

→ buscar el mínimo de $S(\phi)$.

$$Z = \int \mathcal{D}\phi e^{-S(\phi)}$$

$$I = \int_{-\infty}^{\infty} dx e^{-f(x)}$$

$f(x)$ tiene un mínimo en x_0
 $\rightarrow e^{-f(x_0)}$ será el máximo.

$$f(x) = f(x_0) + f'(x_0) \delta x + \frac{1}{2} \delta x^2 f''(x_0) + \dots$$

$x = x_0 + \delta x$ 0

$$I \approx \int_{-\infty}^{\infty} dx e^{-f(x_0) - \frac{1}{2} \delta x^2 f''(x_0)}$$

$$\approx e^{-f(x_0)} \int_{-\infty}^{\infty} dx e^{-\frac{1}{2} \delta x^2 f''(x_0)}$$

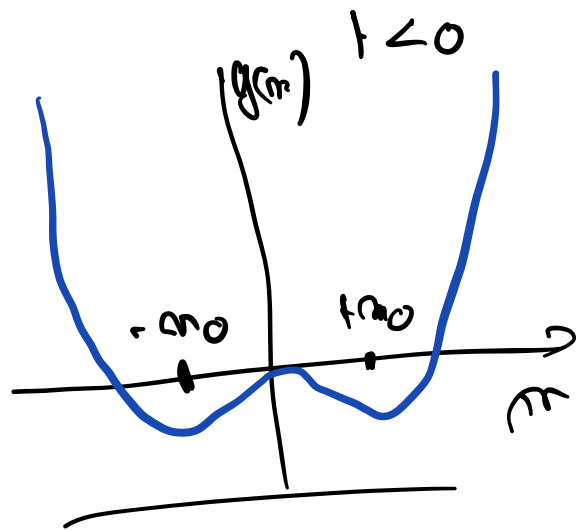
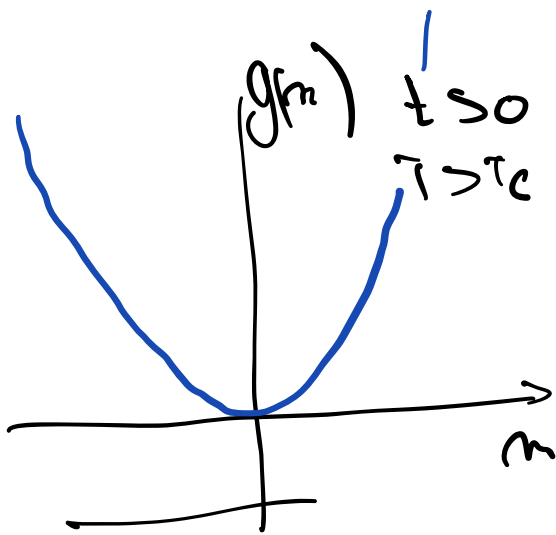
$$= \sqrt{\frac{2\pi}{f''(x_0)}} e^{-f(x_0)}$$

Sea $\phi(r)$ que minimiza $S(\phi)$

\Rightarrow para minimizar $(\nabla\phi)^2$, $\phi = c_1 e^{-m}$

queda: $S(\phi_0) = V \left[\frac{a_2}{2} m^2 + \frac{a_4}{4} m^4 + \frac{a_6}{6} m^6 + \dots \right]$
 $= V g(m)$

$a_4 > 0, a_6 > 0$, $a_2 = a_2 t \begin{cases} > 0 \text{ if } t > 0 \\ < 0 \text{ if } t < 0 \end{cases}$

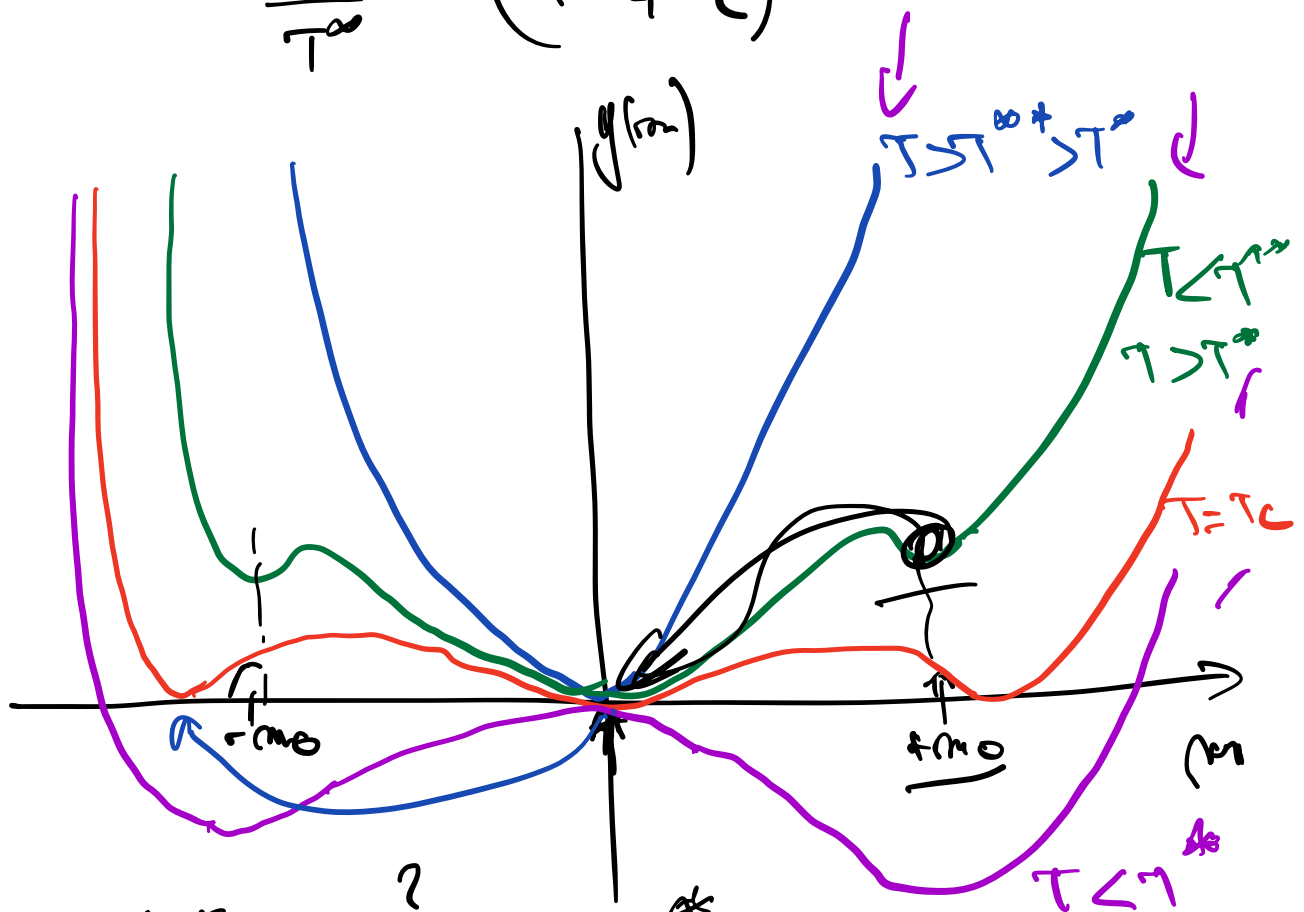


$$m_0 = \frac{\sqrt{\frac{-a_2}{a_4} + \dots}}{\uparrow}$$

$$\text{in } a_4 < 0, a_6 > 0$$

$$S(f_0) = V g(m) = V \left[\frac{a_4}{2} m^2 + \frac{a_4 m^4}{4} + \frac{a_6 m^6}{6} \right]$$

$$t = \frac{T - T^*}{T^*} \quad (T^* \neq T_c)$$



$$T^* = \frac{3a_4}{4a_6} > T^*$$

$$T_c = T^* + \frac{3a_4^2}{16a_6^2}$$

si $T > T^{**}$, el único mínimo está en $m=0$

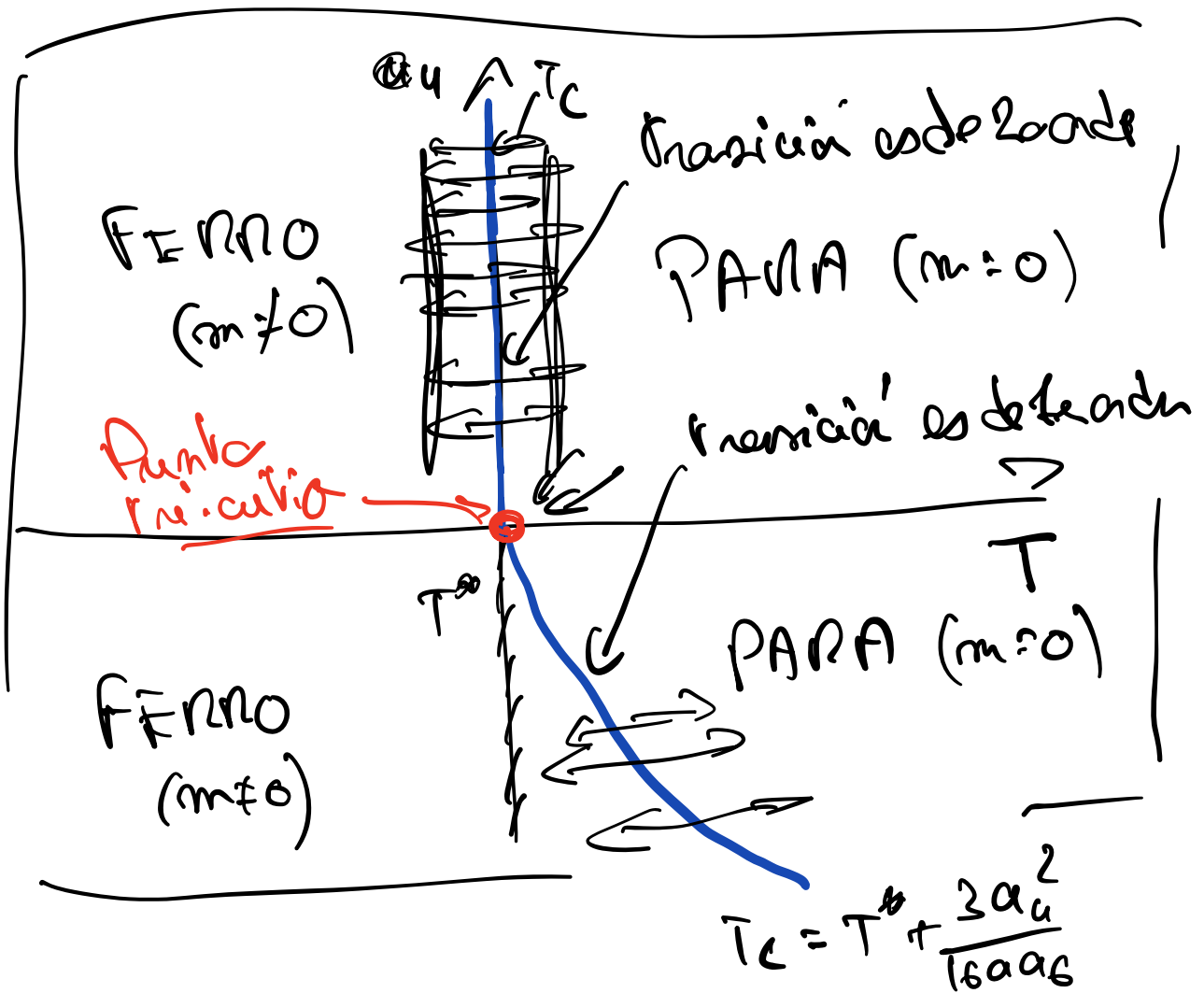
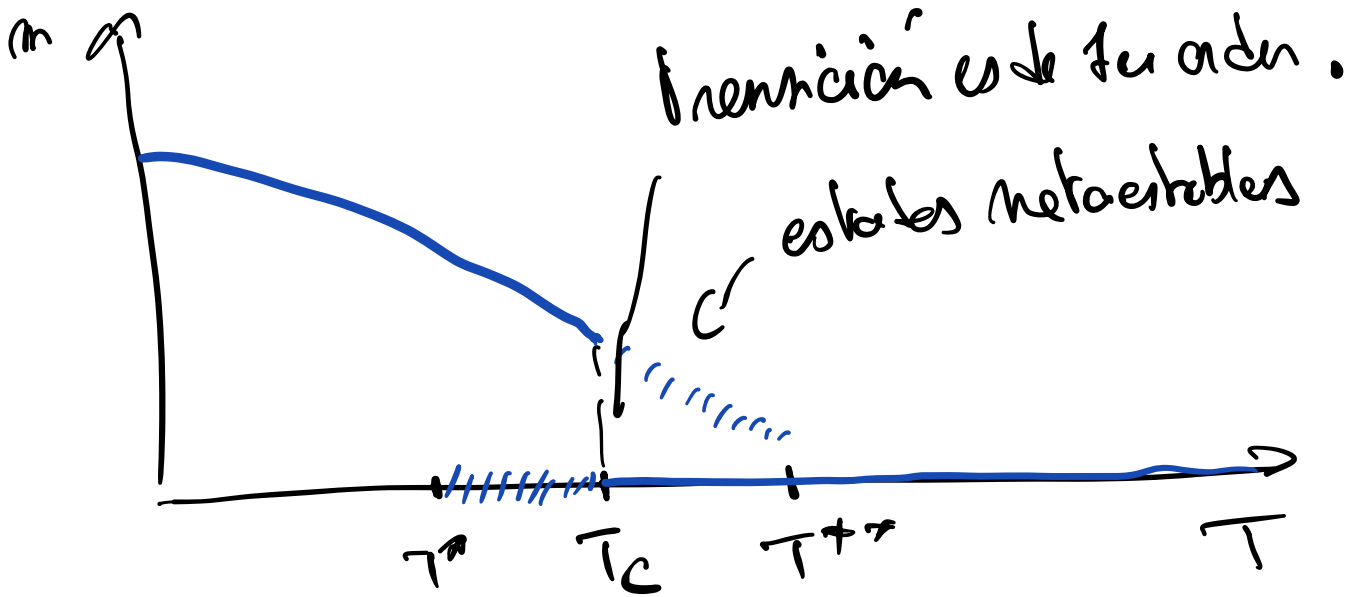
si $T^{**} > T > T_c$

→ el mínimo absoluto está en $m=0$, pero hay mínimos en $\pm m_0$ → estados metaestables

si $T_c > T > T^{**}$

los mínimos absolutos son para $\pm m_0$, y $m=0$ estado metaestable.

si $T < T^{**}$, solo hay mínimos en $\pm m_0$



Aproximación gaussiana:

$$a_4 > 0$$

el mínimo es para $\phi = m = \begin{cases} 0 & \text{si } t > 0 \\ \pm \sqrt{\frac{-a_0}{a_2}} & \text{si } t < 0 \end{cases}$

$$\phi(\vec{r}) = m + \delta\phi$$

$a_2 > 0 \quad (t > 0, T > T_c)$

$$S(\delta\phi) = \int d\vec{r} \left[\frac{c}{2} (\nabla \delta\phi)^2 + \frac{a_2}{2} \delta\phi^2 + \dots \right]$$

$\frac{a_2}{c}$ tiene dimensiones $\frac{1}{\text{longitud}^2}$

$\left(\frac{a_2}{c} = \frac{1}{\xi^2} \right)$ ξ : longitud de correlación

obs $\xi \rightarrow \infty$ si $t \rightarrow 0$ ($0^+ T \rightarrow T_c$)

$$a_2 = at = \frac{a}{T_c} (T - T_c)$$

$$\xi \sim (T - T_c)^{-1/2}; \quad \boxed{\nu = \frac{1}{2}}$$

$$\text{si } T < T_c \quad (a_2 < 0) \quad m \neq m_0 \Rightarrow \sqrt{\frac{-a_2}{a_4}}$$

$$\phi(\vec{r}) = m_0 + \delta\phi(\vec{r})$$

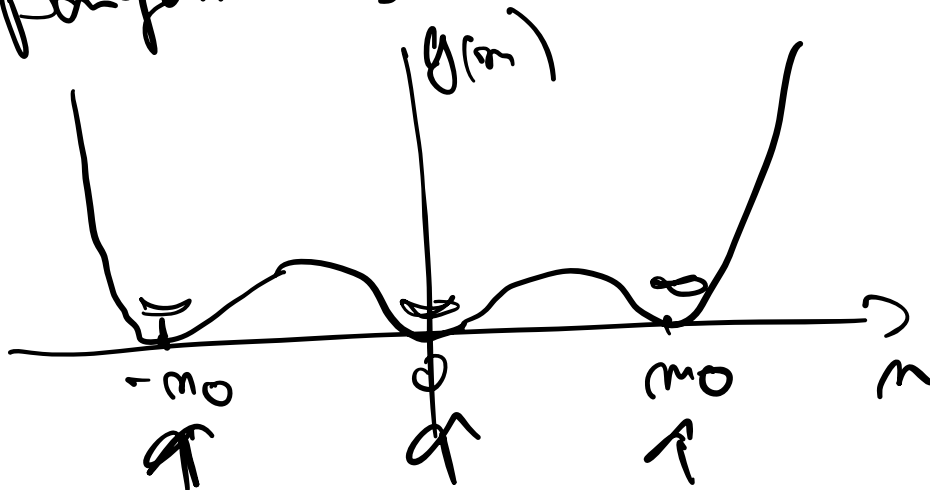
$$S[\delta\phi] = \int d\vec{r} \left[\frac{c}{2} (\nabla \delta\phi)^2 - \underbrace{a_2 \delta\phi^2}_{>0} + \dots \right]$$

$$-\frac{a_2}{c} = \frac{1}{\xi^2}, \quad \rho \sim |\vec{r}|^{-1/2} \quad \boxed{\nu = 1/2}$$

$$m_0 \sim \sqrt{\frac{-a_2}{a_4}} \sim |\vec{r}|^{-1/2} \Rightarrow \boxed{\beta = 1/2}$$

$$\text{si } a_4 < 0$$

Puntos de silla en $T = T_c$



$$\mu_0 = \frac{d^2 g}{d\tau^2} \Big|_{\tau=0} \quad , \quad \mu_m = \frac{d^2 g}{d\tau^2} \Big|_{\tau=\tau_0}$$

$$\phi(\tau) = \begin{cases} 0 + \delta\phi(\tau) \\ \tau_0 + \delta\phi(\tau) \end{cases}$$

$$\delta \int \delta\phi = \int \sqrt{\tau} \left[\frac{c}{2} (\delta\phi)^2 + \frac{\mu_m}{2} \delta\phi^2 \right]$$

μ_0 y $\mu_m \neq 0$ en $\tau = \tau_c$

las longitudes de correlación

$$\xi_0 = \sqrt{\frac{c}{\mu_0}} \quad \xi_m = \sqrt{\frac{c}{\mu_m}}$$

finitas en τ_c

Por último: el punto

tri-crítico $a_4 = 0$

$$S(\phi) = \int d^3x \left[\frac{c}{2} (\nabla\phi)^2 + \underbrace{\frac{a_2}{2}\phi^2 + \frac{a_6}{6}\phi^6}_{\text{potential}} \right]$$

$$a_2 = at \quad \text{si } t > 0 \quad (T > T_c)$$



$m = 0$ mínimo

$$\text{si } t < 0$$

$$\text{dos mínimos, } m = \pm \left(\frac{-at}{a_6} \right)^{1/4}$$

$$\Rightarrow \beta = \frac{1}{4}!$$

Ejemplo: modelo de Blume-Coppe (1966)

$$S_i = \pm 1, 0$$

2-D

$$H = -J \sum_{\langle i,j \rangle} S_i S_j - D \sum_i S_i^2$$

(obs $D \rightarrow \infty \rightarrow \text{Tring}$)

