

El modelo de Ising
 a una Teoría de Campos

1) La Transformación de
Hubbard-Stratonovich

$$\begin{aligned}
 H &= -\frac{1}{2} \sum_{\forall i,j} J_{ij} \underbrace{\sigma_i \sigma_j}_{\in \mathbb{R}} & J_{ij} = J_{ji} \\
 Z &= \sum_{\{\sigma\}} e^{\frac{\beta}{2} \sum_{i,j} \sigma_i J_{ij} \sigma_j} & \text{Diagram: } \text{A wavy line with several parallel lines above it, representing a sum over configurations.}
 \end{aligned}$$

$$\sigma_i = \begin{pmatrix} \sigma_1 \\ \sigma_2 \\ \vdots \\ \sigma_N \end{pmatrix} = \sigma \quad \sigma' = (\sigma_1, \sigma_2, \dots, \sigma_N)$$

J matriz $N \times N$ con entradas

$$J_{ij}$$

$$\sum_{i,j} g_i J_{ij} g_j = g^T J g$$

$$= (g_1, g_2, \dots, g_N) \begin{pmatrix} J_{11} & J_{12} & \dots \\ J_{21} & & \\ \vdots & & \\ & & J_{NN} \end{pmatrix} \begin{pmatrix} g_1 \\ \vdots \\ g_N \end{pmatrix}$$

Si en perdida de generalidad,
todos los autovalores de J son positivos.

$$J \rightarrow J + c \mathbb{1}_{NN} = \tilde{J}$$

$$c > 0$$

$$H \rightarrow \tilde{f}_1 = f_1 + \underbrace{\sum_i c g_i^2}_{\Delta}$$

$$\tilde{f}_1 = f_1 + NC$$

$$\boxed{J > 0} \rightarrow J J^{-1} > 0$$

obs $(\beta_{ij}) = J$ es una matriz

real x simétrica

ej:

$$I = \int_{-\infty}^{\infty} \prod_{i=1}^N dx_i e^{-\frac{1}{2} \sum_{i,j} x_i A_{ij} x_j + \sum_i x_i y_i}$$

con A simétrica $y > 0$, $A^T A = H_{nn}$

y_1, \dots, y_n reales

$$I = \sqrt{\frac{(2\pi)^N}{\text{Det}(A)}} e^{\frac{1}{2} \sum_{i,j} y_i (A^{-1})_{ij} y_j}$$

Indicaciones:

* hacen en combinar de variables en los var. x_i :

$$\begin{pmatrix} x_1 \\ \vdots \\ x_N \end{pmatrix} = \bar{x} = \underbrace{\tilde{x} + A^{-1} \tilde{y}}_{\rightarrow}$$

$$\bar{x} = \begin{pmatrix} y_1 \\ \vdots \\ y_N \end{pmatrix}$$

$$\rightarrow I = e^{\frac{1}{2} y^T A^{-1} y} \int_{-\infty}^{\infty} d\tilde{x}_i e^{-\frac{1}{2} \tilde{x}^T A \tilde{x}}$$

* $\exists \Theta \text{ tq } \Theta^T \Theta = \mathbb{I}_{N \times N}$

$$x \Theta^T A \Theta = D = \begin{pmatrix} \lambda_1 & & & \\ & \ddots & & \\ & & \ddots & \\ & & & \lambda_N \end{pmatrix}$$

$$\Rightarrow \tilde{x} = \Theta \tilde{X}$$

$\left(\det \Theta : 1 \right)$

$$* \int_{-\infty}^{\infty} dx e^{-\frac{1}{2}x^2} = \sqrt{\frac{2\pi}{\lambda}}$$

con la identificación

$$\beta_j \hookrightarrow \gamma_i$$

$$g_i \hookrightarrow x_i$$

$$\phi_i \hookrightarrow x_i$$

$$e^{-\frac{1}{2}\sum_j \beta_j^T \beta_j} = (2\pi)^{-\frac{N}{2}} [\text{Det}(\beta_j)]^{-\frac{1}{2}}$$

$$* \int_{-\infty}^{\infty} \prod_{i=1}^N d\phi_i e^{-\frac{1}{2} \sum_i \phi_i^T \gamma_i^T \gamma_i} e^{i \sum_i g_i \phi_i}$$

$$g_i = \pm 1$$

$$\phi_i \in [-\infty, \infty]$$

$$Z = \left(\frac{1}{2\pi}\right)^{\frac{N}{2}} \left[\text{Det}(\beta \mathcal{S}) \right]^{\frac{1}{2}} \times \int_{\mathbb{R}^N} e^{-\frac{1}{2\beta} \sum_{i,j} \phi_i(\mathcal{S}^\top)_{ij} \phi_j} \sum_{\{\phi\}} e^{\sum_{i=1}^N G_i \phi_i}$$

Obs

$$\sum_{\{\phi\}} e^{\sum_{i=1}^N G_i \phi_i} = \sum_{\{\phi\}} \prod_{i=1}^N e^{G_i \phi_i}$$

$$= \prod_i \left[\sum_{\phi_i = \pm 1} e^{G_i \phi_i} \right] = 2^N \prod_{i=1}^N \text{ch}(\phi_i)$$

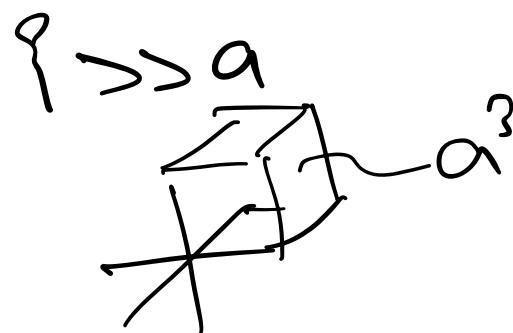
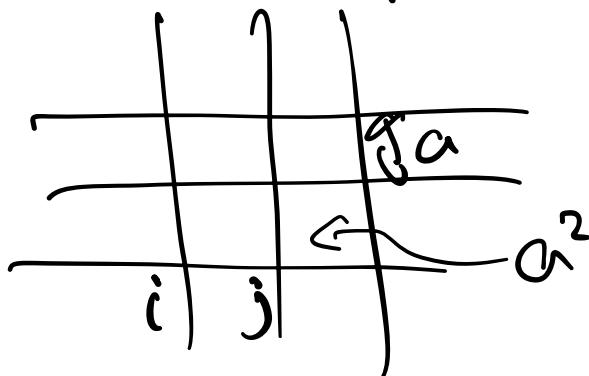
$$Z = \left(\frac{1}{2\pi}\right)^{\frac{N}{2}} \left[\text{Det}(\beta \mathcal{S}) \right]^{\frac{1}{2}} \times \int_{\mathbb{R}^N} e^{-\frac{1}{2\beta} \phi^\top \mathcal{S}^\top \phi - V(\phi)}$$

$$V(\phi) = -N \ln 2 - \sum_{i=1}^N \ln [\text{ch}(\phi_i)]$$

2] Límite al continuo dimension = 2

Cuando $T \sim T_c$, $\{ \rightarrow \infty$

a a es espaciamiento de la red



$$\delta_{i,j} \rightarrow a^2 \delta(\vec{r}_i - \vec{r}_j)$$

$$\sum_j \delta_{i,j} = 1 \rightarrow \int \delta_{i,j} d^2 \vec{r} \delta(\vec{r}_i - \vec{r}_j) = 1$$

$J_{ij} \rightarrow J(|\vec{r}_i - \vec{r}_j|)$
 invariancia para rotación
 y traslación.

$$J'_{ij} \rightarrow J'(|\vec{r}_i - \vec{r}_j|)$$

$$\sum_p J_{ip} J'_{pj} = \delta_{ij}$$

$$\begin{aligned} & \rightarrow \frac{1}{a^d} \int d\vec{r} J(|\vec{r}_i - \vec{r}|) J'(|\vec{r}_j - \vec{r}|) \\ & = a^d S(\vec{r}_i - \vec{r}_j) \quad (*) \end{aligned}$$

→ hacemos la T.F.

$$\hat{\phi}(\vec{k}) = \int d\vec{r} e^{i\vec{k} \cdot \vec{r}} \phi(\vec{r})$$

$$\phi(\vec{r}) = \frac{1}{(2\pi)^d} \int d\vec{k} e^{-i\vec{k} \cdot \vec{r}} \hat{\phi}(\vec{k})$$

obs cono $\phi(\vec{r}) \in \mathbb{R} \Rightarrow \hat{\phi}(\vec{k}) = \hat{\phi}^*(\vec{k})$

$$\hat{J}(\vec{k}) = \int_{\mathbb{R}^3} d\vec{r} e^{i\vec{k} \cdot \vec{r}} J(\vec{r}) \quad x_i \mapsto x_i$$

$$J(\vec{r}) = \frac{1}{(2\pi)^3} \int_{\mathbb{R}^3} d\vec{k} e^{-i\vec{k} \cdot \vec{r}} \hat{J}(\vec{k})$$

$$\hat{J}^{-1}(\vec{k}) = \int_{\mathbb{R}^3} d\vec{r} e^{i\vec{k} \cdot \vec{r}} J(\vec{r})$$

e.g.

$$\int_{\mathbb{R}^3} d\vec{r} e^{i(\vec{k} - \vec{k}') \cdot \vec{r}} = (2\pi)^3 \delta(\vec{k} - \vec{k}')$$

$$\int_{\mathbb{R}^3} d\vec{r}_i d\vec{r}_j e^{i\vec{k} \cdot (\vec{r}_i - \vec{r}_j)} = (2\pi)^3 \delta(\vec{r}_i - \vec{r}_j)$$

$$\hat{J}^{-1}(\vec{k}) = \frac{a^3}{\hat{J}(\vec{k})}$$

$$\begin{aligned}
 & \sum_{i,j} \phi_i \tilde{J}_{ij} \phi_j \rightarrow \\
 & \int d\vec{r} d\vec{r}' \phi(\vec{r}) \tilde{J}^{(1)}(\vec{r}-\vec{r}') \phi(\vec{r}') \\
 & = \frac{1}{(2\pi)^d} \int d\vec{r} \left| \hat{\phi}(\vec{r}) \right|^2 \tilde{J}^{(1)}(\vec{r}) \\
 & = \frac{a^{2d}}{(2\pi)^d} \int d\vec{r} \frac{\left| \hat{\phi}(\vec{r}) \right|^2}{\tilde{J}^{(1)}(\vec{r})}
 \end{aligned}$$

→ el comportamiento a grandes distancias, ↴ pequeño.

$$\begin{aligned}
 \tilde{J}(\vec{r}) &= \tilde{J}(0) + \sum_{\alpha=1,\dots,d} h^\alpha \frac{\partial \tilde{J}}{\partial h^\alpha} \Big|_{h=0} \\
 &+ \frac{1}{2} \sum_{\alpha, \beta} h^\alpha h^\beta \frac{\partial^2 \tilde{J}}{\partial h^\alpha \partial h^\beta} + \dots
 \end{aligned}$$

↳ Oni d+p

$$\overline{\hat{J}(\vec{r})} = \hat{J}(0) + \frac{1}{2} \vec{k}^2 \left(\frac{\partial^2 J}{\partial r_i^2} \right) + \dots$$

- $\int d\vec{r} x_1^2 J(|\vec{r}|)$
 - $\int d\vec{r} x_2^2 J(|\vec{r}|)$
 - $\frac{1}{2} \int d\vec{r} (\vec{r}^2) J(|\vec{r}|)$

Def: alcance efectivo de $J(r)$: ℓ

$$\ell^2 = \frac{\int d\vec{r} \vec{r}^2 J(|\vec{r}|)}{\int d\vec{r} J(|\vec{r}|)} > 0$$

$\hookrightarrow \hat{J}(0)$

$$\hat{J}(\vec{r}) = \hat{J}(0) \left[1 - \ell^2 \frac{\vec{r}^2}{2} + \dots \right]$$

$$\frac{1}{[1 - \ell^2 \frac{\vec{r}^2}{2} + \dots]} \sim [1 + \ell^2 \frac{\vec{r}^2}{2} + \dots]$$

$$\frac{1}{2\beta} \phi^\dagger \tilde{S}' \phi$$

$$\rightarrow \frac{\alpha^2 d}{2\beta S(0)} \int_{\mathbb{R}^n} \left[\frac{d\vec{r}}{(2\pi)^n} \right] \left| \hat{\phi}(\vec{r}) \right|^2 \left(1 + l^2 \vec{k}^2 + \dots \right)$$

$$= \frac{\alpha^2 d}{2\beta S(0)} \int_{\mathbb{R}^n} \left[\phi(\vec{r})^2 + l^2 (\nabla \phi)^2 + \dots \right]$$

$$\begin{aligned} \ln \operatorname{ch} \phi &= \ln \left(1 + \frac{\phi^2}{2} + \frac{\phi^4}{4!} + \dots \right) \\ &= \frac{\phi^2}{2} - \frac{\phi^4}{12} + \dots \end{aligned}$$

$$-\frac{1}{2\beta} \phi^\dagger \tilde{S}' \phi - V(\phi)$$

$$\begin{aligned} e^{-\frac{1}{2\beta} \phi^\dagger \tilde{S}' \phi - V(\phi)} \\ \times e^{-\frac{\alpha^2 d}{2\beta S(0)} \int_{\mathbb{R}^n} \left[\phi^2 + l^2 (\nabla \phi)^2 \right]} \cdot \cancel{\int_{\mathbb{R}^n} \left[\frac{\alpha^2 d}{2} \phi^2 \right]} \\ \rightarrow e^{-\frac{\alpha^2 d}{12} \phi^4 + \dots} \end{aligned}$$

$$\int \vec{J} \cdot d\vec{\ell} \rightarrow \int \vec{J} \cdot d\vec{\ell}$$

$$\mathcal{L} = \det \int \vec{J} \cdot d\vec{\ell}$$

$$-S\{d\ell\}$$

$$S\{d\ell\} = \int d\vec{r} \left[\frac{c}{2} (\vec{\nabla}\phi)^2 + \frac{\alpha_2}{2} \phi^2 + \frac{\alpha_4}{4!} \phi^4 \dots \right]$$

$$c = \frac{l^2}{\beta S(0)}$$

$$\alpha_2 = \left(\frac{b_2 \beta T}{S(0)} - \frac{1}{a^2} \right) a^2 c$$

$$\alpha_4 = \frac{a^3 c}{3} > 0$$

Acción de Ginzburg-Landau

$$S\{\phi\} = \int d\vec{r} \left[\frac{c}{2} (\vec{\nabla}\phi)^2 + \frac{\alpha_2}{2} \phi^2 + \frac{\alpha_4}{4!} \phi^4 \dots \right]$$

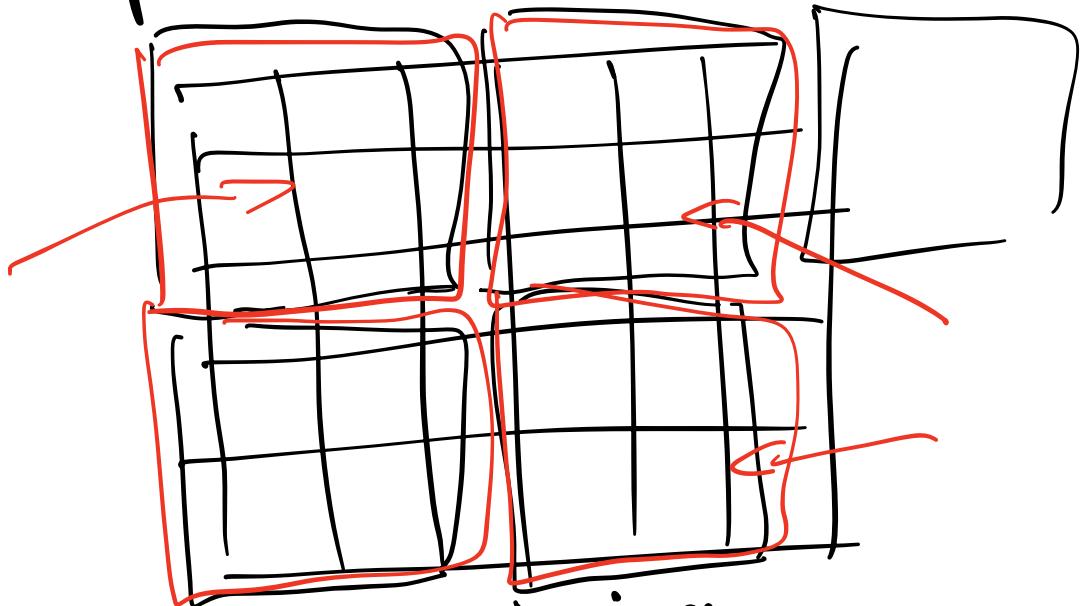
$$Z = \sum_{\text{config}} e^{-\beta H}$$

$\hookrightarrow Z = \int d\phi(\phi) e^{-S[\phi]}$

$$\sigma_i \pm \epsilon \longleftrightarrow \phi(r) \in [0, \omega]$$

$$\sum_{\text{config}} \hookrightarrow \int d\phi(\phi)$$

$$\beta H[\{\sigma_i\}] \longrightarrow S[\phi]$$



Coarse-graining.

$\phi(\vec{r}) \rightarrow$ promedio de varias $T_i \leq T$

Obs $S\{f\}$ simétrica \mathbb{Z}_2

$$\begin{cases} \phi(\vec{r}) \rightarrow \phi(\vec{r}) \\ \phi(\vec{r}) \rightarrow -\phi(\vec{r}) \end{cases}$$

$$a_2 = a(T - T_c)$$

$$T > T_c \quad a_2 > 0$$

$$T < T_c \quad a_2 < 0$$

El mecanismo de $S\{f\}$

$$S\{f\} = \int d\vec{r} \left[C(\bar{\phi}\phi)^2 + \frac{a_2}{2} \phi^2 + \frac{a_4}{4!} \phi^4 \right]$$

$$C, a_4 > 0$$

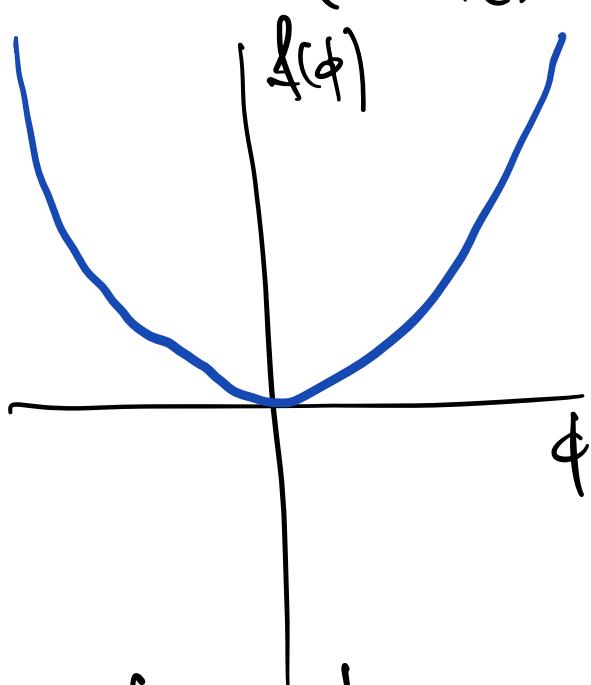
$c > 0$ el minimo

$\nabla \phi = \vec{0} ! \rightarrow \phi$ es homogeneo.

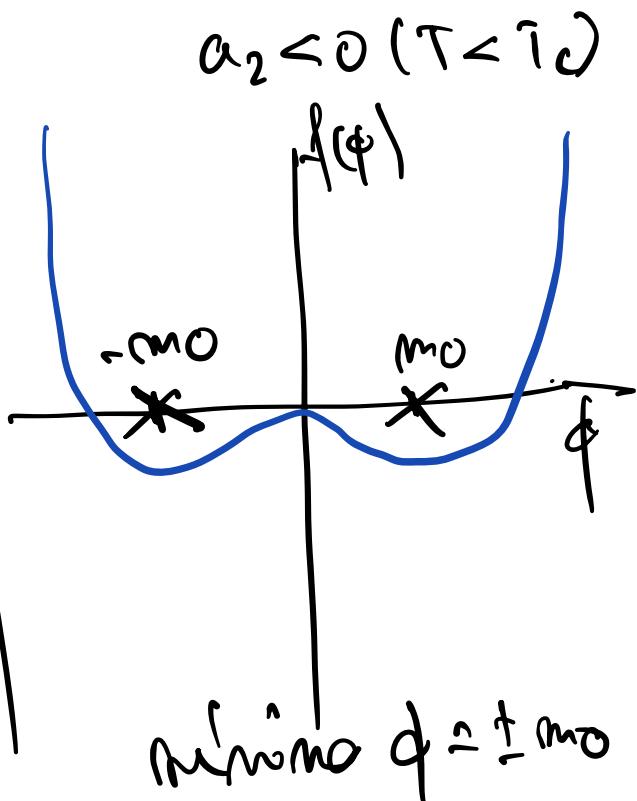
$$\frac{a_2}{2} \phi^2 + \frac{a_4}{4} \phi^4$$

$$f(\phi) = \frac{a_2}{2} \phi^2 + \frac{a_4}{4} \phi^4 \quad \begin{cases} a_4 > 0 \\ a_2 > 0 \text{ si } T > T_c \\ a_2 < 0 \text{ si } T < T_c \end{cases}$$

$a_2 > 0 (T > T_c)$



minimo $\phi = 0$



minimo $\phi = \pm \phi_{MO}$

$T > T_c \rightarrow \text{PARA}$

$T < T_c \rightarrow \text{FERRO}$