

R.G. perturbativo en

Teoría de Campos

$$S = \int d^D \vec{r} \left[\frac{t}{2} \dot{\phi}^2 + \frac{K}{2} (\nabla \phi)^2 + \underline{\mu \phi^4 + M_0 \phi^6} \right]$$

Transformación de escala

$$\vec{r} = b \vec{r}', \quad \vec{q} \rightsquigarrow b' \vec{q}'$$

$$K = K', \quad \phi = b^{\frac{D-2}{2}} \phi', \quad t = b^2 t'$$

$$\underline{\mu = b^{-(4+D)} \mu}, \quad M_0 = b^{-6+2D} M_0$$

$$M_8 = b^{-8+3D} M_8$$

para la dimensión crítica
superior es $D = 9$ (i.e. $M^D = 9$
a escala)

$\hat{m} \quad D < 4 \quad u \nearrow \text{camb}$

$D > 4 \quad u \searrow \text{camb}$

Trabajo con un el parámetro $4-D = \epsilon$

→ esto es lo más tenían en cuenta
la fluctuaciones.

$z \rightarrow e^{-S}$
no es ~~peso~~

$z = \int d\theta e^{-S}$
 \uparrow

→ para hacer eso, pasamos a las
variables de Fourier:

$$\mathcal{L} = \int d\vec{q} e^{-\underbrace{\int d^D r [\frac{k}{2} (\nabla \phi)^2 + \frac{t}{2} \phi^2]}_{S_0}} - \mathcal{U}$$

donde $\mathcal{U} = \mu \underbrace{\int d^D r \phi^4}_{\text{---}}$

def:

$$m(\vec{q}) = \int d^D r e^{i\vec{q} \cdot \vec{r}} \phi(\vec{r})$$

$$\phi(\vec{r}) = \int \frac{d^D \vec{q}}{(2\pi)^D} e^{-i\vec{q} \cdot \vec{r}} m(\vec{q})$$

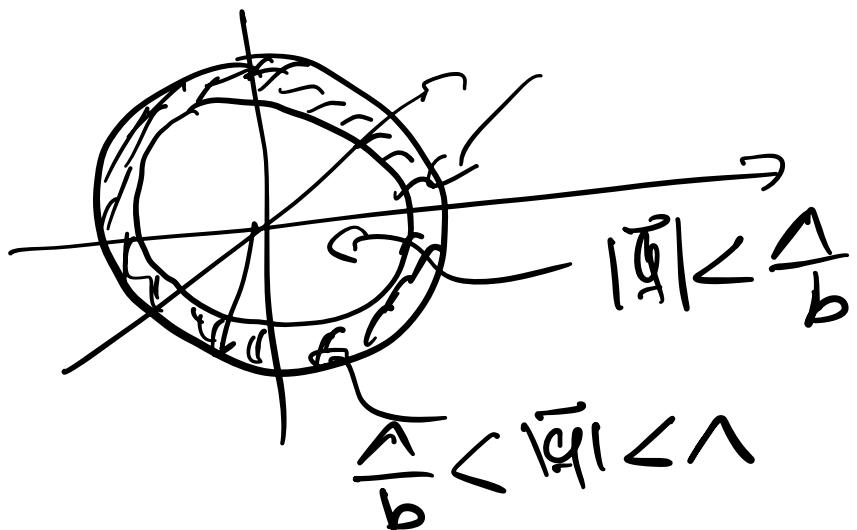
$$S_0 = \int \frac{d^D \vec{q}}{(2\pi)^D} \left(\frac{k}{2} \vec{q}^2 + \frac{t}{2} \right) |m(\vec{q})|^2$$

$$\mathcal{U} = \mu \int \frac{d\vec{q}_1 d\vec{q}_2 d\vec{q}_3}{(2\pi)^{3D}} (m(\vec{q}_1) m(\vec{q}_2) m(\vec{q}_3)) \\ m(-\vec{q}_1 \cdot \vec{q}_2 \cdot \vec{q}_3)$$

aquí \hat{q} tiene un cut-off inicial
que es $\Lambda \sim \frac{1}{a_0}$ a_0 = espacio del
bárd original.

La idea del R.C.

es separa



ejemplo

$$I = \int dx dy e^{f(x,y)}$$

$$= \int dx e^{f_{\text{eff}}(x)}$$

dónde $e^{f_{\text{eff}}(x)} = \int dy e^{f(x,y)}$

$$\int D(m(\vec{q})) = \int D(\tilde{m}(\vec{q})) D\zeta(\vec{q})$$

$$m(\vec{q}) = \begin{cases} \tilde{m}(\vec{q}) & \text{si } 0 < |\vec{q}| < \frac{\Lambda}{b} \\ \zeta(\vec{q}) & \text{si } \frac{\Lambda}{b} \leq |\vec{q}| \leq 1 \end{cases}$$

la idea es integrar sobre $\zeta(\vec{q})$ más más.

$$\text{h}^* \mathcal{U} = 0$$

$$Z = \int_{-\infty}^{\infty} D(m(\bar{q})) D(g(\bar{q})) e^{-\int_{\frac{m(\bar{q})}{2}}^{\frac{g(\bar{q})}{2}} (t + \frac{k\bar{q}^2}{2}) (m(t))^2 dt}$$

$$Z_0 = \int_{-\infty}^{\infty} D(g(\bar{q})) e^{-\int_{\frac{m(\bar{q})}{2}}^{\frac{g(\bar{q})}{2}} (t + \frac{k\bar{q}^2}{2}) (g(t))^2 dt}$$

$$SF_g^0 = \ln Z_0$$

$$\langle \theta \rangle = \frac{1}{2\pi} \int D(\bar{q}) \theta e^{-S(\bar{q})}$$

$$Z = \int D(m(\bar{q})) \underbrace{D(g(\bar{q}))}_{S_{eff}(m(\bar{q}))} e^{-S}$$

$$= \int D(g(\bar{q})) e^{-S}$$

En Self $\{m(\vec{q})\}$

$$= g f_0^0 + \int \frac{d\vec{q}}{(2\pi)^D} \left[\frac{t + \kappa q^2}{z} \right] |m(\vec{q})|^2$$

$\vec{q} \perp \vec{u}$

- $m \langle e^{-u} \rangle$

et $m \langle e^{-u} \rangle$

$$= - \langle u \rangle_0 + \frac{1}{2} (\langle u^2 \rangle_0 - \langle u \rangle_0^2)$$

~~\uparrow~~ + - \uparrow

$\langle u_{[m, \sigma]} \rangle_0$

$$= m \int \frac{d\vec{q}_1 d\vec{q}_2 d\vec{q}_3}{(2\pi)^{3D}} S(\vec{q}_1 + \vec{q}_2 + \vec{q}_3 + \vec{q}_4)$$

$\langle m(\bar{q}_1) \ m(\bar{q}_2) \ m(\bar{q}_3) \ m(\bar{q}_4) \rangle$

podrá ser $\hat{m}(\bar{q}_r)$ ó $\hat{\bar{m}}(\bar{q}_r)$

dependiendo de si q_r es tránsito
 \leftarrow y \rightarrow o es \circlearrowleft y \circlearrowright

es fácil ver, por直观性, que solo
los rítmicos con m^* para $\Gamma(\bar{q})$
serán resultados no-nulos.

* O " $\sigma(\bar{q})$ " \rightarrow $\downarrow \hat{m}(\bar{q}) \rightarrow u \hat{q}^{(v)}_r$

+ $\downarrow \Gamma(\bar{q})$ \rightarrow de que contiene $\hat{m}(\bar{q})$
 \rightarrow Relaciones impalancadas

* $\downarrow \Gamma(\bar{q})$ y $\downarrow \hat{m}(\bar{q}) \rightarrow$ renormalizar
el resultado $\frac{1}{2} (m(\bar{q}))^2$

$$\rightarrow -12\mu \int \frac{d\vec{q}_1 \dots d\vec{q}_4}{(2\pi)^D} (2\pi)^D \delta(\vec{q}_1 + \dots + \vec{q}_4)$$

$$(2\pi)^D \frac{\delta(\vec{q}_1 + \vec{q}_3)}{t + k \vec{q}_1^2} \hat{m}(\vec{q}_3) \hat{m}(\vec{q}_4)$$

$$= -12\mu \underbrace{\int_0^{\frac{1}{b}} \frac{d\vec{k}}{(2\pi)^D} \frac{1}{2 + k^2}}_{q < \frac{1}{b}} \times \int \frac{d\vec{q}}{(2\pi)^D} |\hat{m}(\vec{q})|^2$$

bajo esta integración de los $\delta(\vec{q})$

$$S_{\text{eff}} \approx S$$

$$\text{para } t \rightarrow \tilde{t} = t + 12\mu \int \frac{d\vec{n}}{(2\pi)^D} \frac{1}{t + k^2}$$

~~$\frac{1}{b} < q < 1$~~

+ el cambio de escala al orden "0"

$$t \rightarrow t' = b^2 t$$



$$t'_b = b^2 \left[t + 12\mu \int_{\frac{1}{(2\pi)^D}}^{\frac{1}{t+Kh^2}} \right]$$

$\frac{1}{b} < k < 1$

$$\mu_b = b^{q-1} \mu$$

abaae, $b \approx (1+\delta)$

$$b^2 \approx (1+2\delta)$$

$$b^\alpha \approx (1+\alpha\delta)$$

$$D \quad t'_b = t + dt$$

$$Y \int \frac{d\lambda}{(2\pi)^D} \frac{1}{t+Kh^2} = \frac{S_D}{(2\pi)^D} \int_0^D \frac{d\lambda}{t+K\lambda^2}$$

$$\frac{1}{b} < k < 1 \quad dE \approx \lambda^D S_D d\lambda$$

$$\Rightarrow \frac{dt}{dl} = 2t + \frac{12\mu \frac{S_D}{(2\pi)^D} \lambda^D}{t + K\lambda^2}$$

$$\frac{du}{dl} = (u-i)\mu$$

Si se toma en cuenta los términos

$$\langle u^2 \rangle_0 - \langle u \rangle_0^2$$

$$\frac{dt}{dl} = 2t + \frac{12\mu \frac{S_D}{(2\pi)^D} \lambda^D}{t + K\lambda^2} - A\mu^2$$

$$\frac{du}{dl} = (u-i)\mu - \frac{36 \frac{S_D}{(2\pi)^D} \lambda^D}{(t + K\lambda^2)^2} \mu^2$$

Punto fijo: (t^*, u^*)

$$\frac{dt^*}{du} = 0 \quad \frac{du^*}{du} \approx 0$$

$$t^* = -\frac{6\mu^* \frac{S_D}{(2\pi)^D} \lambda^D}{t^* + K \lambda^2} + \frac{A}{2} \mu^{*2}$$

$$\mu^* = \frac{(t^* + K \lambda^2)^2}{36 \frac{S_D}{(2\pi)^D} \lambda^D (u - 1)}$$

$\epsilon = q - D$, suponemos que $D \geq 4$

$$\epsilon \ll 1$$

→ Desarrollar en potencias de ϵ

→ Fijaros el orden 1 en ϵ

$$u^* \sim \epsilon, t^* \sim \epsilon$$

$$t^* \ll \kappa \lambda^2$$

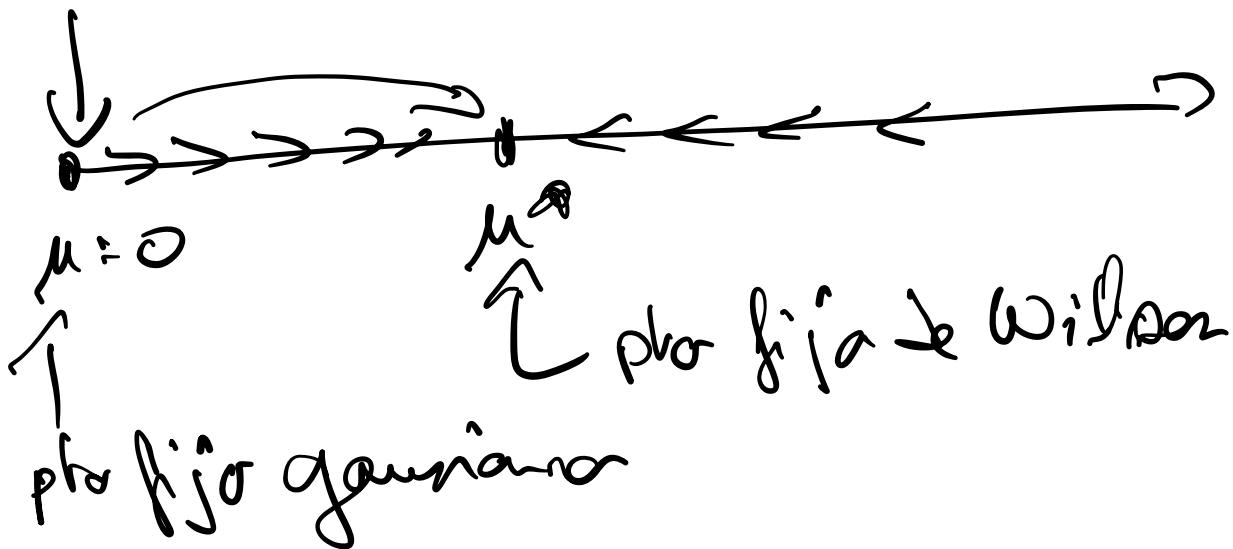
$$t^* + \kappa \lambda^2 \sim \kappa \lambda^2$$

$$\frac{S_D}{(2\pi)^D} \sim \frac{S_q}{(2\pi)^d} + \mathcal{O}(\epsilon)$$

\Rightarrow

$$t^* = -\frac{\kappa \lambda^2}{G} \epsilon + \mathcal{O}(\epsilon^2)$$

$$\mu^* = \frac{\kappa^2}{36 \frac{S_q}{(2\pi)^d}} \epsilon + \mathcal{O}(\epsilon^2)$$



$$t = f + \delta t \quad u = u^* + \delta u$$

$$\frac{d}{dt} \begin{pmatrix} \delta t \\ \delta u \end{pmatrix} = \begin{pmatrix} 2 - \frac{\epsilon}{3} & * \\ O(\epsilon^2) & -\epsilon \end{pmatrix} \begin{pmatrix} \delta t \\ \delta u \end{pmatrix}$$

$$\delta t \sim (\delta t)^{-1}, \quad \delta u \sim (\delta t)^{-1}$$

$$\delta t \sim \delta^{-\gamma} \Rightarrow \Delta = \frac{1}{2 - \frac{\epsilon}{3}}$$

$$\Delta \approx \frac{1}{2} + \frac{1}{12} \epsilon + O(\epsilon^2)$$

Obs si ponemos $\Delta = 3$ ($\epsilon = 1$)

$$V_{D=3} = 0,58 \quad (\text{tol. temp., } D \approx 0,6)$$

Obs se generaliza para
el modelo OCN

$$S = \int d\tau \left[\frac{k}{n} \sum_{m=1}^n (\nabla \phi_m)^2 + \frac{1}{c} \sum_{m=1}^n \dot{\phi}_m^2 + \mu \left(\sum_{m=1}^n \phi_m^2 \right) \right]$$

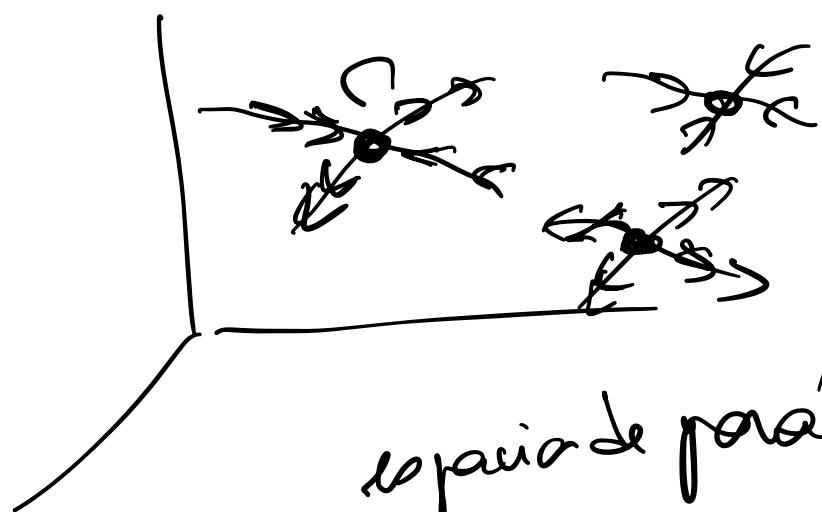
$$\boxed{\frac{dt}{d\tau} = 2t + \frac{4\mu(n+2)K\lambda^D}{t + K\lambda^2} \cdot \Lambda \mu^2 \dots}$$

$$\boxed{\frac{d\mu}{dt} = (4-d)\mu - \frac{4(n+2)K\lambda^D}{(t + K\lambda^2)^2} \mu^2 \dots}$$

$$\begin{cases} \mu^* = \frac{\lambda^2}{4(n+2)} \in +O(\epsilon^2) \\ t^* = -\frac{(n+2)}{2(n+1)} K \lambda^2 \epsilon + O(\epsilon^2) \end{cases}$$

$$\gamma D = \frac{1}{2} + \frac{1}{4} \frac{n+2}{n+8} \epsilon + O(\epsilon^2)$$

3) Vecindad de un punto crítico



espacio de parámetros

en cada punto crítico "C"

se definen como los conjuntos

generados de ese punto anfibio

" $T_i(\bar{x})$ " de dimensión k

escala τ_i :

Caso C es afilico \rightarrow inv.
de escala,

$$\overline{\langle \hat{\phi}_i(\tau) \hat{\phi}_i(\tau') \rangle} \sim \frac{1}{|\tau'|^{2x_i}}$$

Soluciones de \mathbb{C} parcial

$$S = S_C + \underbrace{\int d^D \tau g_i \hat{\phi}_i}_{\sim L^{-x_i}}$$

$$[\hat{\phi}_i] \sim L^{-x_i}$$

$$[g_i] \sim L^{x_i-1}$$

\rightarrow transf. de escala:

$$\begin{aligned} L &\rightarrow L' \text{ tq } L = bL' \\ g_i &\rightarrow g'_i b^{x_i-1} \end{aligned}$$

$\text{si } x_i > D \quad g_i' \downarrow \text{const}$

$\text{si } x_i < D \quad g_i' \nearrow \text{const}$

$\text{si } x_i > D, \text{ una perturbación en } g_i, \phi_i \text{ mantiene alejado de } C$

\rightarrow perturbación bocón irrelevant

$\text{si } x_i < D \rightarrow g_i' \nearrow \text{const}$

\rightarrow se aleja de $C \rightarrow$ perturbación relevante.